

LINEAR ANALYSIS PRELIM EXAM

Autumn 2014

- Do as many of the eight problems as you can.
- Four completely correct solutions will be a pass;
- A few complete solutions will count more than many partial solutions. Always carefully justify your answers.
- If you skip a step or omit some details in a proof, point out the gap and, if possible, indicate what would be required to fill it in.

Notation

- $\mathbb{R}^{n \times m}$ denotes the $n \times m$ real matrices.
- $\mathbb{C}^{n \times m}$ denotes the $n \times m$ complex matrices.
- \mathbb{S}^n denotes the real symmetric matrices
- $H \in \mathbb{S}^n$ is said to be *positive definite* ($H > 0$) if $x^T H x > 0$ for all $x \in \mathbb{R}^n$ with $x \neq 0$.
- $H \in \mathbb{S}^n$ is said to be *positive semi-definite* ($H \geq 0$) if $x^T H x \geq 0$ for all $x \in \mathbb{R}^n$.
- The singular values of a matrix A are the eigenvalues of the matrix $\sqrt{A^* A}$.
- $\mathcal{S}(\mathbb{R}^n)$ denotes the Schwartz space of smooth rapidly decaying functions.
- $\mathcal{S}'(\mathbb{R}^n)$ denotes the space of tempered distributions.
- A function $f \in L^1(\mathbb{R}^n)$ acts as a tempered distribution on $\phi \in \mathcal{S}$ by

$$\langle f, \phi \rangle = \int_{\mathbb{R}^n} f(x) \phi(x) d^n x$$

- $H^2(\mathbb{R}^2)$ is the closure of $C_0^\infty(\mathbb{R}^2)$ in the norm,

$$\|u\|_{H^2(\mathbb{R}^2)}^2 := \|u\|_{L^2}^2 + \|\Delta u\|_{L^2}^2$$

- In \mathbb{R}^2 , $\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$
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1. Let $A \in \mathbb{R}^{m \times n}$, $W \in \mathbb{R}^{m \times m}$, and $V \in \mathbb{R}^{n \times n}$ with W and V symmetric.

(a) Show that V is positive definite on $\ker A$, i.e.,

$$u^T V u > 0 \quad \text{whenever } u \neq 0 \text{ and } u \in \ker A,$$

if and only if there is a $\kappa > 0$ such that the matrix $V + \kappa A^T A$ is positive definite.

(b) Suppose V is positive semidefinite on $\ker A$, i.e.,

$$u^T V u \geq 0 \quad \text{whenever } u \in \ker A.$$

Show that the matrix $M := \begin{bmatrix} V & A^T \\ A & 0 \end{bmatrix}$ is nonsingular if and only if V is positive definite on $\ker A$ and the rank of A is m .

(c) Show that the matrix

$$T := \begin{bmatrix} V & A^T \\ A & W \end{bmatrix}$$

is positive definite if and only if the matrices V and $W - AV^{-1}A^T$ are positive definite.

2. Let $A \in \mathbb{C}^{n \times n}$ and $\epsilon > 0$. Show that the three sets $\mathcal{A}, \mathcal{B}, \mathcal{C}$ defined below are equal.

$$\mathcal{A} = \{ \lambda \in \mathbb{C} \mid \lambda \in \Lambda(X), \|A - X\| \leq \epsilon \},$$

$$\mathcal{B} = \{ \lambda \in \mathbb{C} \mid \|(A - \lambda I)^{-1}\| \geq \epsilon^{-1} \text{ or } (A - \lambda I) \text{ is singular.} \},$$

$$\mathcal{C} = \{ \lambda \in \mathbb{C} \mid \sigma_{\min}(A - \lambda I) \leq \epsilon \},$$

where we have used the operator 2-norm and $\sigma_{\min}(A - \lambda I)$ is the smallest singular value of $(A - \lambda I)$.

3. Let $m(x) \in C^1([0, 1])$ and $\lambda \in \mathbb{C}$. Consider the boundary value problem

$$\begin{aligned} \left(\frac{d}{dx} + m(x) - \lambda \right) u &= f \\ u(0) &= u(1) \end{aligned}$$

Let $G(\lambda)$ denote the solution operator as a mapping from $f \in L^2(0, 1)$ to $u \in L^2(0, 1)$.

(a) Find an explicit formula for $G(\lambda)f$.

(b) Find an explicit formula for the eigenvalues of the boundary value problem (i.e. the values of λ for which $G(\lambda)$ does not exist).

(c) Prove that, if λ is not an eigenvalue, $G(\lambda)$ is a compact operator which maps $L^2(0, 1)$ to itself.

4. Suppose $U : \mathbb{R} \rightarrow \mathbb{R}$ is \mathcal{C}^1 . If we interpret U as the potential energy of a particle at position x , then $-U'(x)$ (minus the derivative of U) is the force acting on the particle, so (for a particle with mass 1) Newton's law of motion is the second order ODE

$$\frac{d^2x}{dt^2} = -U'(x(t)). \quad (1)$$

For example, for a simple harmonic oscillator (spring), we could have $U(x) = \frac{1}{2}kx^2$ for some $k > 0$.

- (a) Rewrite equation (1) as a first-order system.
 (b) The kinetic energy of a particle is $\frac{1}{2}(\dot{x})^2$, so the total energy is

$$E(t) = \frac{1}{2}(\dot{x}(t))^2 + U(x(t)).$$

where the dot $\dot{} = \frac{d}{dt}$ means derivative with respect to time. Show that if x solves (1), then $E(t)$ is constant, i.e., energy is conserved.

- (c) Suppose that U is bounded from below (that is, there exists $C \in \mathbb{R}$ such that $U(x) \geq C$ for all $x \in \mathbb{R}$). Prove that every solution of (1) exists for all time ($t \rightarrow \pm\infty$).
 (d) Show that if $U(x) = -x^4$, then the solution of (1) satisfying the initial conditions $x(0) = 0$, $\dot{x}(0) = 1$ blows up in finite time.

5. Consider the map

$$Mf = \int_0^1 |x - y|f(y)dy$$

mapping $L^2(0, 1)$ into continuous (but not necessarily bounded) functions on the real line.

- (a) Show that the image of the unit ball in $L^2(0, 1)$ are uniformly Lipschitz continuous; i.e.

$$|Mf(a) - Mf(b)| \leq C|a - b|$$

where C depends only on $\|f\|_{L^2(0,1)}$.

- (b) Find the codimension 2 subspace of $L^2(0, 1)$ that maps into $L^2(\mathbb{R})$.
Hint: On this subspace, Mf is identically zero outside $(0, 1)$.
 (c) Show that M is a compact and injective operator from this subspace into $L^2(\mathbb{R})$.

6. Prove the existence of a solution $u \in H^2(\mathbb{R}^2)$ that satisfies

$$\Delta u - u = F(x, u)$$

under the hypotheses that the $F \in C^\infty(\mathbb{R}^2 \times \mathbb{R}^1)$ satisfies

$$\|F(x, 0)\|_{L^2} \quad \text{is sufficiently small}$$

$$|F(x, a) - F(x, b)| \leq (|a| + |b|) |a - b| \quad \text{for all real } x, a, b$$

Hint: Use Fourier transform to estimate the H^2 norm of the solution u to the linear PDE $\Delta u - u = f(x)$ in terms of the L^2 norm of f ; then define a mapping from a ball in H^2 to itself, and show it's a contraction if $\|F(x, 0)\|_{L^2}$ is small enough. The fact that the supremum ($L^\infty(\mathbb{R}^2)$) norm is bounded by a constant times the $H^2(\mathbb{R}^2)$ norm may be useful. This fact is a form of the Sobolev embedding theorem.

7. The two definitions below describe how the tempered distributions, r_P and r_D , act on $\phi \in \mathcal{S}$. Prove that the two definitions define the same tempered distribution.

$$\langle r_P, \phi \rangle := \lim_{\epsilon \downarrow 0} \int_{|x| > \epsilon} \frac{1}{x} \phi(x) dx$$

$$\langle r_D, \phi \rangle := \langle \partial_x \log(|x|), \phi \rangle$$

Part of the problem is to prove that each does indeed define a tempered distribution.

8. (a) Prove that the linear map

$$T\phi = \phi(|x|^2) \quad x \in \mathbb{R}^2$$

maps $\mathcal{S}(\mathbb{R}^1)$ to $\mathcal{S}(\mathbb{R}^2)$.

- (b) By duality, T induces a map

$$T^* : \mathcal{S}'(\mathbb{R}^2) \rightarrow \mathcal{S}'(\mathbb{R}^1)$$

Every $f \in \mathcal{S}'(\mathbb{R}^2)$ defines a distribution in $\mathcal{S}'(\mathbb{R}^2)$. For such a distribution, T^*f is also a function in $\mathcal{S}'(\mathbb{R}^1)$. Find an explicit expression for the function T^*f (i.e. write a formula for its value at every $t \in \mathbb{R}$, not just a formula for its action as a distribution). *Hint: Use polar coordinates*